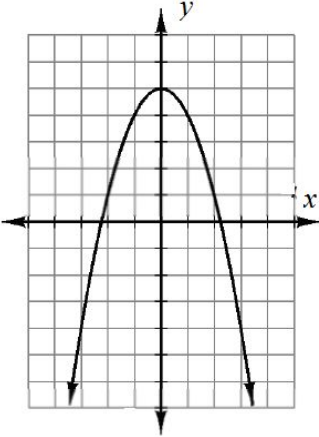
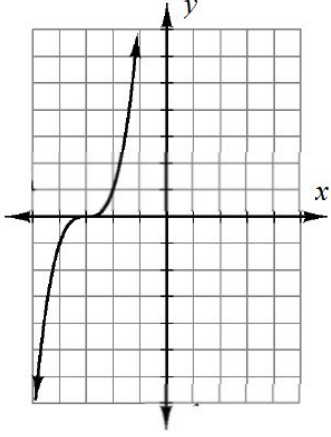
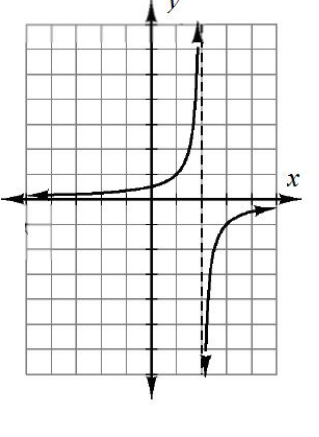
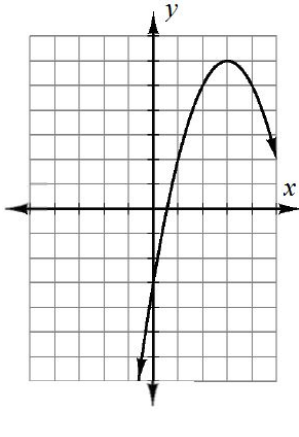
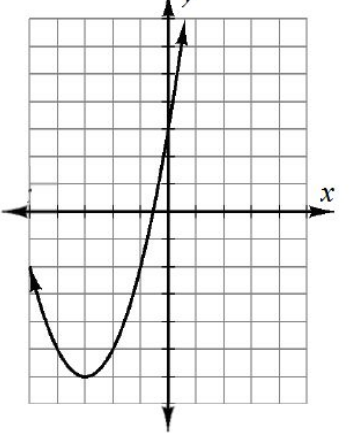


### PRACTICE #3 : Graphs & Equations of Transformations

For each graph, identify the **family of functions**, the **locator point**, the **orientation**, and the **stretch factor**. Then write a possible **equation** for the graph.

<p>1. Family:</p> <p>Vertex <math>(h, k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 	<p>2. Family:</p> <p>Point of Inflection <math>(h, k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 
<p>3. Family:</p> <p>Asymptotes <math>(x = h \text{ \&amp; } y = k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 	<p>4. Family:</p> <p>Vertex <math>(h, k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 
<p>5. Family:</p> <p>Vertex <math>(h, k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 	<p>6. Family:</p> <p>Point of Inflection <math>(h, k)</math>:</p> <p>Orientation:</p> <p>Stretch/Compression?</p> <p>Equation:</p> 